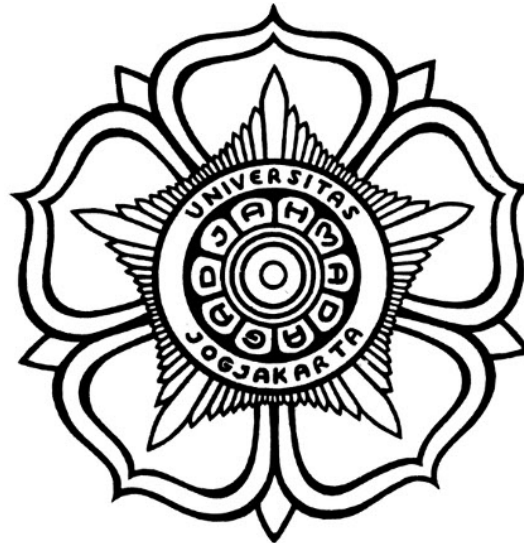


**STUDY ON SLIDING MODE APPROACH FOR ATTITUDE
CONTROL ON UAV QUADCOPTERS**

THESIS



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