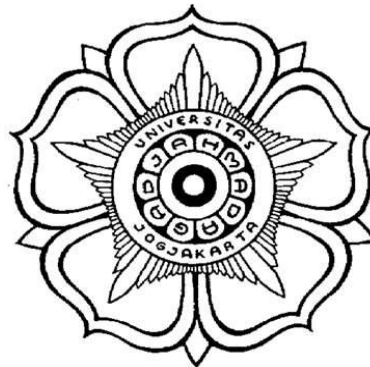


SKRIPSI

**IMPLEMENTASI SISTEM KENDALI GERAK LURUS ROBOT *THREE*
OMNI - DIRECTIONAL DRIVE DENGAN METODE PID FUZZY**

***IMPLEMENTATION OF THREE OMNI – DIRECTIONAL DRIVE ROBOT
STRAIGHT MOVEMENT CONTROL SYSTEM WITH FUZZY PID
METHOD***



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**PROGRAM STUDI ELEKTRONIKA DAN INSTRUMENTASI
JURUSAN ILMU KOMPUTER DAN ELEKTRONIKA
FAKULTAS MATEMATIKA DAN ILMU PENGETAHUAN ALAM
UNIVERSITAS GADJAH MADA
YOGYAKARTA**

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