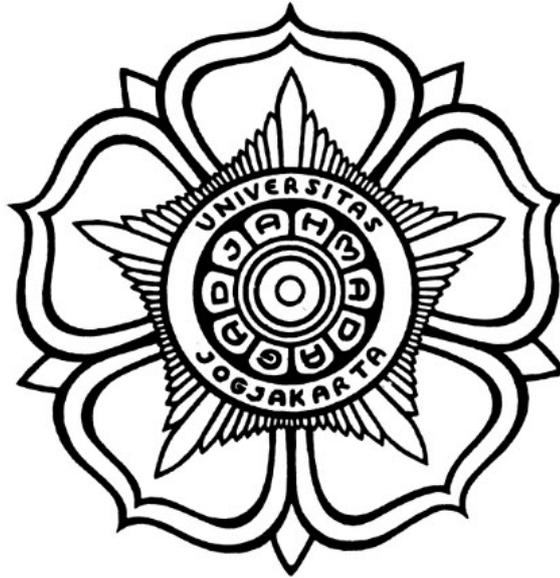


**COVERAGE CONTROL WITH COLLISION AVOIDANCE FOR  
NETWORKED NON-HOLONOMIC ROBOTS**

**FINAL PROJECT REPORT**



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