

DAFTAR PUSTAKA

- [1] R. N. Jazar, *Theory of Applied Robotics : Kinematics, Dynamics, and Control* Second Edition, New York: Springer, 2006.
- [2] S. H. a. M. V. Mark W. Spong, *Robot Modeling & Control* first Edition, USA: A Wiley-Interscience, 2006.
- [3] Arduino, “Arduino Due,” Arduino, [Online]. Available: <https://www.arduino.cc/en/Main/ArduinoBoardDue>. [Diakses 22 10 2015].
- [4] M. G. X. T. a. H. K. K. Alexander Esbrook, “Control of System with Hysteresis via Servocompensation and Its Application to Nanopositioning,” *2010 American Control Conference*, pp. 6531-6536, 2010.
- [5] A. L. Benesik, “Appropriate Mathematical Model of DC Servo Motors Applied in Scara Robots,” *Acta Polytechnica Hungarica*, vol. 1, pp. 99-111, 2004.
- [6] I. M. A. H. A. E. Ahmed Z Alassar, “Modeling and Control of 5 DOF Robot Arm Using Supervisory Control,” *Computer and Automation Engineering (ICCAE), 2010 The 2nd International Conference on*, vol. 3, pp. 351-355, 26-28 Feb. 2010.
- [7] A. S. Morris, *Measurement & Instrumentation Principle* 3rd Edition, Oxford: Butterworth-Heinemann, 2001.