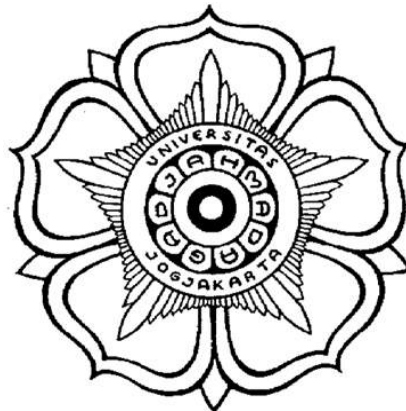


## SKRIPSI

**SISTEM KENDALI *HIGH SPEED FLIP* PADA *QUADROTOR*  
BERBASIS *LINEAR QUADRATIC REGULATOR (LQR)*  
DENGAN PARAMETERISASI *QUARTEMNION***

***HIGH SPEED FLIP CONTROL SYSTEM ON THE QUADROTOR  
BASED ON LINEAR QUADRATIC REGULATOR (LQR) WITH  
QUARTEMNION PARAMETERIZATION***



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