

## DAFTAR PUSTAKA

- [1] E. Abbasi, "Development and Implementation of a Adaptive Fuzzy Control System for a VTOL Vehicle in Hovering Mode," *Int. J. Control Theory Comput. Model.*, vol. 7, no. 1/2, pp. 1–14, Apr. 2017.
- [2] M. B. Hurd and R. D. of M. E. University of Nevada, *Control of a quadcopter aerial robot using optic flow sensing*. 2013.
- [3] "Jurnal Teknologi Elektro, Universitas Mercu Buana ISSN : 2086-9479 PERANCANGAN SIMULASI KENDALI," vol. 6, no. 2, pp. 123–135, 2015.
- [4] A. Saelan, "Logika Fuzzy," *Strukt. Disk.*, vol. 1, no. 13508029, pp. 1–5, 2009.
- [5] R. Oktarianda, "Politeknik negeri sriwijaya palembang 2014," 2014.
- [6] B. T. Atmojo, S. R. Sulistyanti, and E. Nasrullah, "Model Sistem Kendali Pintu Otomatis Menggunakan Barcode Berbasis PC ( Personal Computer ) Pada Gerbang Laboratorium Teknik Elektro Unila," *Rekayasa dan Teknol. Elektro*, vol. 7, no. 2, pp. 47–55, 2013.
- [7] P. Atiqah, "Strategi jepang dalam mempertahankan dominasi ekspor robot di china," pp. 1–15.
- [8] M. Ali, "Pembelajaran Perancangan Sistem Kontrol Pid Dengan Software Matlab," *J. Edukasi@Elektro*, vol. 1, no. 1, pp. 1–8, 2004.
- [9] L. P. Ayuningtias, "ANALISA PERBANDINGAN LOGIC FUZZY METODE TSUKAMOTO , SUGENO , DAN MAMDANI ( STUDI KASUS : PREDIKSI JUMLAH PENDAFTAR MAHASISWA BARU FAKULTAS SAINS DAN TEKNOLOGI UNIVERSITAS ISLAM NEGERI SUNAN GUNUNG DJATI BANDUNG ) Laras P : Analisa Perbandingan Logic ... L," vol. 10, no. 1, 2017.
- [10] S. Kusumadewi, "Analisis dan Desain Sistem Fuzzy Menggunakan Toolbox Matlab," 2002.
- [11] G. N. P. Pratama, A. Dharmawan, and C. Atmaji, "Implementasi Kendali Logika Fuzzy pada Robot Line Follower," *Univ. Gadjah Mada*,

- Yogyakarta*, vol. 4, no. 1, pp. 45–56, 2014.
- [12] S. Kasus, D. I. Kecamatan, and B. Sundi, “LOGIKA FUZZY DALAM SISTEM PENDUKUNG RASKIN,” vol. 3, no. 1, pp. 93–104, 2016.
- [13] A. Soeprijanto, “Desain Kontroler Primemover Generator,” vol. 2009, no. semnasIF, pp. 76–83, 2009.
- [14] G. A. W. S, E. Susanto, D. Ph, and A. S. Wibowo, “Kestabilan Sikap Kamera Berbasis Sensor IMU dengan Metode Fuzzy Logic Control The Stability of Camera Based On IMU Sensor with Fuzzy Logic Control,” vol. 4, no. 2, pp. 1505–1511, 2017.
- [15] I. Oktariawan, Martinus, and Sugiyanto, “Pembuatan Sistem Otomasi Dispenser Menggunakan Mikrokontroler Arduino Mega 2560,” *J. FEMA*, vol. 1, no. 2, pp. 18–24, 2013.
- [16] U. Papa, G. Ariante, and G. Del Core, “UAS Aided Landing and Obstacle Detection Through LIDAR-Sonar data,” *2018 5th IEEE Int. Work. Metrol. Aerosp.*, pp. 478–483, 2018.