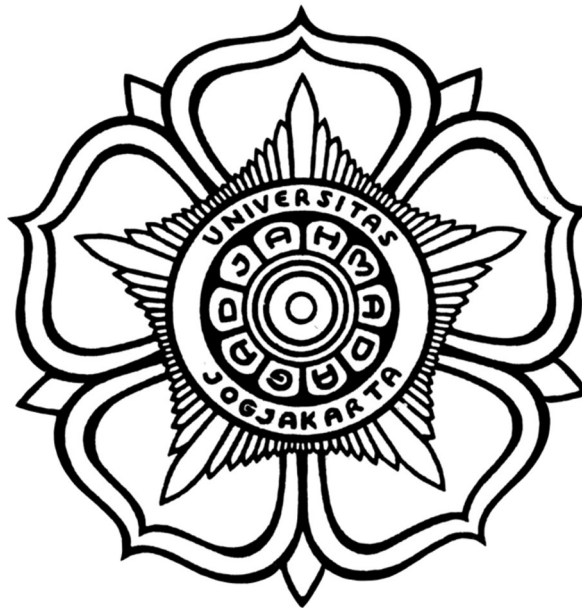


**IMPLEMENTATION OF QUADROTOR UAV PROPORTIONAL-
DERIVATIVE STABILIZATION ON QUATERNIONS WITH
MADGWICK FILTER**

FINAL PROJECT REPORT



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