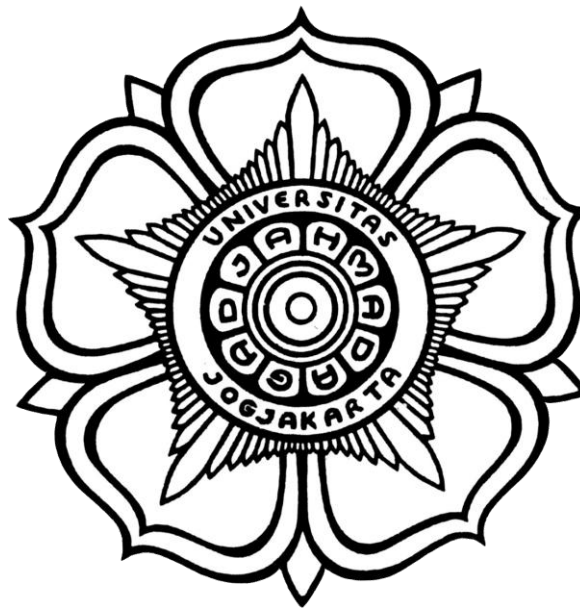


**COVERAGE CONTROL UNDER SENSING CONSTRAINTS
AND OBSTACLE AVOIDANCE ON MULTI-AGENT SYSTEMS**

THESIS



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