

DAFTAR PUSTAKA

- Atmel, 2008, *8-bit Microcontroller with 32K Bytes In-System Programmable Flash*, <http://www.atmel.com/Images/doc2467.pdf>, diakses 2 April 2018
- Dharmawan, Budi, 2017, Penerapan Metode Denavit-Hartenberd Pada Perhitungan Inverse Kinematic Gerakan Lengan Robot, ResearchGate, ISSN-L : 2579-6410
- De Luca, Alessandro. 2012. *Inverse Kinematic*, SAPIENZA Press, Brazil.
- Kamal, 2011. *Infrared Proximity Sensor Part*, Stevanu, United Kingdom
- Kavraki, Lydia E, 2007, *Protein Inverse Kinematic and The Loop Closure Problem*, Creative Commons, USA
- Khidir, Malik, 2014. Sistem Kontrol Gerak Robot *Hexapod* Menggunakan Algoritme *Tigerpod Gait* Berbasis *Inverse Kinematic*, Skripsi, Universitas Gadjah Mada, Yogyakarta
- Kucuk, Serdar, et.al, 2013. *Robot Kinematics : Forward and Inverse Kinematic*, INTECH, China
- McKinsey, 2012. *Sensing and Sensor Fundamentals*, Unknown Publisher, USA.
- Mittal, R.K. 2005. *Robotics and Control. New Delhi*, Tata McGraw-Hill Publishing Company Limited.
- Prabantara, Sapriando, 2013. Kendali Robot Lengan *Dental Light* Menggunakan Analisis Kinematika Balik Berbasis Pengolahan Citra Digital Berdasarkan Isyarat Tangan, Skripsi, Universitas Gadjah Mada, Yogyakarta
- Senoaji. *Modeling Moving Object Control System for Motorized Arm Robot Using ADAM Series*, Politeknik Elektronika Negeri Surabaya, Surabaya
- Servocity, 2010. *How Do Servos Work ?*, http://servocity.com/html/how_do_servos_work_.html, diakses 3 April 2018
- Singh, 2013. *Infrared Proximity Sensor Theory and Application*, Unknown Publisher, New Delhi, India
- Stuart, Barbara, 2010. *Infrared Spectroscopy, Fundamentals and Application*, WILEY, USA
- Yao, Ming, 2012. *Mathematics for Inverse Kinematic*, Technical Animation, China