

CONTENTS

ENDORSEMENT PAGE	ii
STATEMENT.....	iii
PAGE OF DEDICATION	iv
PREFACE.....	v
CONTENTS	vi
LIST OF TABLES.....	ix
LIST OF FIGURES	x
NOMENCLATURE AND ABBREVIATION	xiii
INTISARI.....	xiv
ABSTRACT	xv
CHAPTER I Introduction	1
1.1 Research Background.....	1
1.2 Problem Identification	2
1.3 Aim of the Study	2
1.4 Research Limitations	3
1.5 Benefits of the Study.....	3
1.6 Systematics of Writing	3
CHAPTER II Literature Review and Basic Theories	4
2.1 Literature Review	4
2.1.1 Wind Energy Conversion Systems	4
2.1.2 Inverter Control	5
2.1.3 Hybrid Operation of DFIG-Based WECS with IBRs	6
2.1.4 Oscillations	6
2.2 Basic Theories	6
2.2.1 Power System Stability	6
2.2.2 Reference Frame Transformation	7
2.2.3 Phase-Locked Loop	10
2.2.4 Wind Energy Conversion Systems (WECSs)	10
2.2.5 Inverter Control	11
2.2.5.1 Grid-Following (GFL) Control.....	11
2.2.5.2 Grid-Forming (GFM) Control.....	11
2.2.6 Network Model.....	13
CHAPTER III Research Methodology	14
3.1 Tools and Materials	14
3.2 Network Model	14
3.2.1 RL or L Network Model	14



3.2.2	<i>RLC</i> or <i>LC</i> Network Model	14
3.3	Phase-Locked Loop Model	15
3.4	DFIG Model.....	16
3.4.1	Dynamic Model	16
3.4.1.1	DFIG Mechanical Model.....	16
3.4.1.2	DFIG Stator and Rotor Model	16
3.4.1.3	DC-Link Model	18
3.4.2	Control Structure	18
3.4.2.1	RSC Control Structure.....	18
3.4.2.2	GSC Control Structure	19
3.5	Inverter Model	20
3.5.1	GFL Control Structure	20
3.5.2	GFM Control Structure	22
3.6	System Model and Parameters	23
3.6.1	Standalone Inverter.....	23
3.6.2	Standalone DFIG.....	23
3.6.3	Hybrid System	24
3.7	Model Verification	25
3.8	Controller Parameters.....	26
3.8.1	DFIG WECS Controller	26
3.8.1.1	RSC Controller Parameters	26
3.8.1.2	GSC Controller Parameters	26
3.8.2	Inverter Controller	27
3.9	Stability Analysis	27
3.9.1	Small Signal Analysis	27
3.9.1.1	Linearization	27
3.9.1.2	Eigenvalue	29
3.9.1.3	Participation Factor	29
3.9.2	Dynamic Time-Domain Analysis	30
3.10	System Testing and Simulation	30
3.10.1	Small-Signal Analysis: Variation of Line Impedance	30
3.10.2	Small-Signal Analysis: Variation of Synchronization Parameters ..	31
3.10.3	Dynamic Time-Domain Analysis	32
3.11	Research Flow.....	32
CHAPTER IV	RESULTS AND DISCUSSION	35
4.1	Small-Signal Analysis: Impact of Line Impedance to System Stability	35
4.1.1	Standalone Operation	35
4.1.1.1	Standalone GFL.....	35
4.1.1.2	Standalone GFM.....	35



4.1.1.3	Standalone DFIG	38
4.1.2	Hybrid Operation of DFIG-GFL	39
4.1.3	Hybrid Operation of DFIG-GFM	40
4.2	Small-Signal Analysis: Impact of Synchronization Control to System Stability.....	43
4.2.1	Standalone Operation	43
4.2.1.1	Standalone GFL: Impact of GFL PLL Bandwidth to System Stability.....	43
4.2.1.2	Standalone GFM: Impact of GFM Virtual Inertia Constant to System Stability	45
4.2.1.3	Standalone GFM: Impact of GFM Virtual Damping Constant to System Stability	46
4.2.1.4	Standalone DFIG: Impact of DFIG PLL Bandwidth to System Stability.....	48
4.2.2	Hybrid Operation of DFIG-GFL	50
4.2.2.1	Impact of GFL PLL Bandwidth to System Stability with DFIG-GFL.....	50
4.2.2.2	Impact of DFIG PLL Bandwidth to System Stability with DFIG-GFL.....	51
4.2.3	Hybrid Operation of DFIG-GFM	55
4.2.3.1	Impact of GFM Virtual Inertia Constant to System Stability with DFIG-GFM	55
4.2.3.2	Impact of GFM Damping Constant to System Stability with DFIG-GFM.....	57
4.2.3.3	Impact of DFIG PLL Bandwidth to System Stability with DFIG-GFM.....	59
4.3	Dynamic Time-Domain Simulation.....	59
4.3.1	Standalone Operation	59
4.3.1.1	GFL.....	59
4.3.1.2	GFM.....	61
4.3.1.3	DFIG	63
4.3.2	Hybrid Operation.....	63
4.3.2.1	DFIG-GFL	63
4.3.2.2	DFIG-GFM	67
CHAPTER V	Conclusion and Future works	70
5.1	Conclusion	70
5.2	Future Works	71
REFERENCES		72