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Lampiran

❖ **ASTM D638M**

❖ **ASTM D790M**

Standard Test Method for TENSILE PROPERTIES OF PLASTICS (METRIC)¹

This standard is issued under the fixed designation D 638M; the number immediately following the designation indicates the year of original adoption or, in the case of revision, the year of last revision. A number in parentheses indicates the year of last reappraisal. A superscript epsilon (ϵ) indicates an editorial change since the last revision or reappraisal.

1. Scope

1.1 This test method covers the determination of the tensile properties of plastics in the form of standard dumbbell-shaped test specimens when tested under defined conditions of pretreatment, temperature, humidity, and testing machine speed.

1.2 This test method can be used for testing materials of any thickness up to 10 mm. However, for testing specimens in the form of thin sheeting, including film less than 1.0 mm, Test Methods D 882 is the preferred test method. Materials with a thickness greater than 10 mm must be reduced by machining.

NOTE 1—This test method is the metric counterpart of Test Method D 638.

NOTE 2—This test method may be used for testing phenolic resin molded or laminated materials. However, where these materials are used as electrical insulation, such materials should be tested in accordance with ASTM Method D 229, Testing Rigid Sheet and Plate Materials Used for Electrical Insulation,^{2,3} and ASTM Method D 651, Test for Tensile Strength of Molded Electrical Insulating Materials.³

NOTE 3—This test method is not intended to cover precise physical procedures. It is recognized that the constant-rate-of-crosshead-movement type of test leaves much to be desired from a theoretical standpoint, that wide differences may exist between rate of crosshead movement and rate of strain between gage marks on the specimen, and that the testing speeds specified disguise important effects characteristic of materials in the plastic state. Further, it is realized that variations in the thicknesses of test specimens, which are permitted by these procedures, produce variations in the surface-volume ratios of such specimens, and that these variations may influence the test results. Hence, where directly comparable results are desired, all samples should be equal thickness. Special additional tests should be used where more precise physical data are needed.

1.3 *This standard may involve hazardous materials, operations, and equipment. This standard does not purport to address all of the safety problems associated with its use. It is the responsibility of whoever uses this standard to consult and*

establish appropriate safety and health practices and determine the applicability of regulatory limitations prior to use.

2. Applicable Documents

2.1 ASTM Standards:

D 618 Methods of Conditioning Plastics and Electrical Insulating Materials for Testing²

D 638 Test Method for Tensile Properties of Plastics²

D 882 Test Methods for Tensile Properties of Thin Plastic Sheetings²

D 883 Definitions of Terms Relating to Plastics²

D 4066 Specification for Nylon Injection and Extrusion Materials⁴

E 4 Practices for Load Verification of Testing Machines^{4,5}

E 83 Practice for Verification and Classification of Extensometers⁵

3. Significance and Use

3.1 This test method is designed to produce tensile property data for the control and specification of plastic materials. These data are also useful for qualitative characterization purposes and for research and development.

3.2 Tensile properties may vary with specimen preparation and with speed and environment of testing. Consequently, where precise comparative results are desired, these factors must be carefully controlled.

3.2.1 It is realized that a material cannot be

¹ This test method is under the jurisdiction of ASTM Committee D-20 on Plastics and is the direct responsibility of Subcommittee D20.10 on Mechanical Properties.

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² Annual Book of ASTM Standards, Vol 08.01.

³ Annual Book of ASTM Standards, Vol 10.01.

⁴ Annual Book of ASTM Standards, Vol 08.03.

⁵ Annual Book of ASTM Standards, Vol 03.01.

specimens shall be prepared having their long axes parallel with, and normal to, the direction of anisotropy.

7. Conditioning

7.1.1 **Conditioning**—Condition the test specimens at $\pm 2^\circ\text{C}$ and $50 \pm 5\%$ relative humidity for not less than 40 h prior to test in accordance with Procedure A of Methods D 618, for those conditioning is required. In cases of sagging, the tolerances shall be $\pm 1^\circ\text{C}$ and $\pm 2\%$ relative humidity.

7.1.1.1 **Conditioning**—Condition the test specimens at $\pm 2^\circ\text{C}$ and $50 \pm 5\%$ relative humidity for not less than 40 h prior to test in accordance with Procedure A of Methods D 618, for those conditioning is required. In cases of sagging, the tolerances shall be $\pm 1^\circ\text{C}$ and $\pm 2\%$ relative humidity.

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test. Rate of motion of the driven grip or fixture when the testing machine is running idle may be used, if it can be shown that the resulting speed of testing is within the limits of variation allowed.

9.2 Choose the speed of testing from Table 1. Determine this chosen speed of testing by the specification for the material being tested, or by agreement between those concerned. When the speed is not specified, use the lowest speed shown in Table 1 for the specimen geometry being used, which gives rupture within $\frac{1}{2}$ to 5 min testing time.

9.3 Modulus determinations may be made at the speed selected for the other tensile properties or as required by the specification.

10. Procedure

10.1 Measure the width and thickness of rigid flat specimens (Fig. 1) with a suitable micrometer to the nearest 0.02 mm at several points along their narrow sections. Measure the thickness of nonrigid specimens (produced by a Type M-II die) in the same manner with the required dial micrometer. Take the width of this specimen as the distance between the cutting edges of the die in the narrow section. Record the minimum values of cross-sectional area so determined.

10.2 Place the specimen in the grips of the testing machine, taking care to align the long axis of the specimen and the grips with an imaginary line joining the points of attachment of the grips to the machine. The distance between the ends of the gripping surfaces, when using flat specimens, shall be as indicated in Fig. 1. Tighten the grips evenly and firmly to the degree necessary to prevent slippage of the specimen during the test but not to the point where the specimen would be crushed.

10.3 Attach the extension indicator.

10.4 Set the speed of testing at the proper rate as required in Section 9, and start the machine.

10.5 Record load-extension curve of the specimen.

10.6 Record the load and extension at the yield point (if one exists) and the load and extension at the moment of rupture.

permanently damaged. A broad-range incremental extensometer or hard rule technique may be needed when such materials are taken to rupture.

11. Calculations

11.1 **Tensile Strength**—Calculate the tensile strength by dividing the maximum load in newtons by the original minimum cross-sectional area of the specimen in square meters. Express the result in pascals and report it to three significant figures as "Tensile Strength at Yield" or "Tensile Strength at Break," whichever term is applicable. When a nominal yield or break load less than the maximum is present and applicable, it may be desirable also to calculate, in a similar manner, the corresponding "Tensile Stress at Yield" or "Tensile Stress at Break" and report it to three significant figures (Annex Note A1.1).

11.2 **Percent Elongation**—If the specimen gives a yield load that is larger than the load at break, calculate "Percent Elongation at Yield." Otherwise, calculate "Percent Elongation at Break." Do this by reading the extension (change in gage length) at the moment the applicable load is reached. Divide that extension by the original gage length and multiply by 100. Report "Percent Elongation at Yield" or "Percent Elongation at Break" to two significant figures. When a yield or breaking load less than the maximum is present and of interest, it is desirable to calculate and report both "Percent Elongation at Yield" and "Percent Elongation at Break" (Annex Note A1.2).

11.3 **Modulus of Elasticity**—Calculate the modulus of elasticity by extending the initial linear portion of the load-extension curve and dividing the difference in stress corresponding to any segment of section on this straight line by the corresponding difference in strain. Compute all elastic modulus values using the average initial cross-sectional area of the test specimens in the calculations. Express the result in pascals and report to three significant figures.

11.4 For each series of tests, calculate the arithmetic mean of all values obtained and

report it as the "average value" for that property in question.

11.5 Calculate the standard deviation as follows and report it to three significant figures:

$$s = \sqrt{\sum X^2 - n\bar{X}^2 / (n - 1)}$$

where:

s = estimated standard deviation.
 X = value of single observation.
 n = number of observations, and
 \bar{X} = arithmetic mean of the set of observations.

12. Report

12.1 The report shall include the following information:
12.1.1 Complete identification of material tested, including type, source, lot number, previous history, etc.

12.1.2 Method of preparing test specimens, previous history, etc.

12.1.3 Type of test specimen and dimensions.

12.1.4 Conditioning procedure used.

12.1.5 Atmospheric conditions in test.

12.1.6 Number of specimens tested.

12.1.7 Speed of testing.

12.1.8 Tensile strength at yield or average value, and standard deviation.

12.1.9 Tensile stress at yield or average value, and standard deviation.

12.1.10 Percent elongation at yield (or both as applicable), average value and deviation.

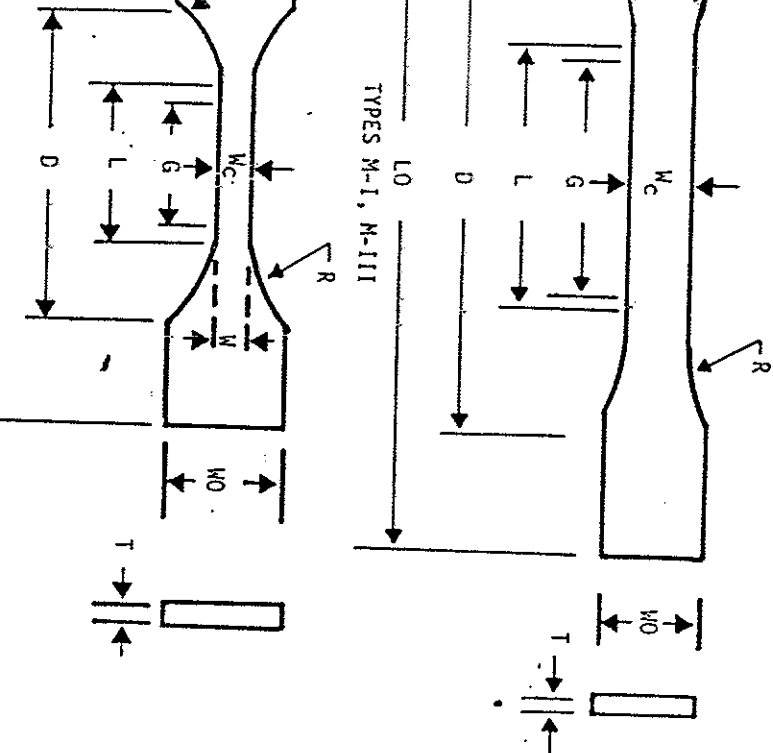
12.1.11 Modulus of elasticity, average value and standard deviation, and standard deviation.

12.1.12 Date of test.

13. Precision and Bias

13.1 A task group has been formed to study the precision and bias statement for this method.

* A report on a limited comparison between 1 and D 638M are available on loan from ASTM Request RR-D20-1088.



Classification	Specimen Type	Speed of Testing, mm/min	Nominal Strain Rate at Start of Test, mm/mm.min
Rigid and semirigid	M-I	5 ± 25 % 50 ± 10 % 500 ± 10 %	0.1 1 10
	M-II	5 ± 25 % 50 ± 10 % 500 ± 10 %	0.15 1.5 15
	M-III	1 ± 25 % 10 ± 25 % 50 ± 10 %	0.1 1 1.5
	Nonrigid	100 ± 25 % 50 ± 10 % 500 ± 10 %	1 10 15

^a Select the lowest speed that produces rupture in 1/10 to 5 min for the specimen geometry being used (see 9.2).

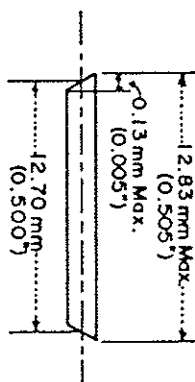
^b See Definitions D 883 for definitions.

^c The initial rate of straining cannot be calculated exactly for dumbbell-shaped specimens because of extension, both in the reduced section, outside the gage length and in the fillets. This initial strain rate can be measured from the initial slope of the tensile strain-versus-time diagram.

Specimen Dimensions for Thickness, T, mm^a

Dimensions (see drawings)	10 or Under			4 or Under			Toler
	Type M-I	Type M-II	Type M-III	Type M-I	Type M-II	Type M-III	
W—Width of narrow section ^{a,b}	10	6	2.5	±0.1	±0.1	±0.1	
L—Length of narrow section	60	33	10	±0.1	±0.1	±0.1	
WO—Width of overall, min ^c	20	25	10	±0.1	±0.1	±0.1	
LO—Length overall, min ^c	150	115	60	no t	no t	no t	
G—Gage length ^c	50	—	7.5	±0.1	±0.1	±0.1	
G—Gage length ^c	—	25	—	±0.1	±0.1	±0.1	
D—Distance between grips	115	80	25	±5	±5	±5	
R—Radius of fillet	60	14	15	±1	±1	±1	
RO—Outer radius (Type II)	—	25	—	±1	±1	±1	

^a The width at the center W, shall be plus 0.00 mm, minus 0.10 mm compared with width W at other parts of section. Any reduction in W at the center shall be gradual, equally on each side so that no abrupt changes in time be taken into account when calculating width of the specimen. Thus a typical section of a molded Type M-I specimen the maximum allowable draft, could be as follows:



^c Test marks or initial extensometer span.

^d Thickness, T, shall be 3 ± 0.4 mm for all types of molded specimens where possible. If specimens are made sheets or plates, thickness T, may be the thickness of the sheet or plate provided this does not exceed the range 5 intended specimen type. For sheets of nominal thickness greater than 10 mm, the specimens shall be machined equal in thickness, for use with the Type M-I specimen. For sheets of nominal thickness between 10 and 50 mm ap equal amount shall be machined from each surface. For thicker sheets both surfaces of the specimen shall be machined the location of the specimen with reference to the original thickness of the sheet, shall be noted. Tolerances on it than 10 mm shall be those standard for the grade of material tested.

^e A Type M-I specimen, having an overall width of 20 mm and an overall length of 215 mm is the preferred specimen shall be used whenever possible.

^f Overall widths greater than the minimum indicated may be desirable for some materials in order to avoid break grips.

^g Overall lengths greater than the minimum indicated may be desirable either to avoid breaking in the grips special test requirements.

FIG. 1—Continued.

ANNEX

(Mandatory Information)

A1. DEFINITIONS OF TERMS AND SYMBOLS RELATING TO TENSION TESTING PLASTICS.

A1.1 *tensile stress (nominal)*—the tensile load per unit area of minimum original cross section, within the gage boundaries, carried by the test specimen at any given moment. It is expressed in force per unit area, usually in megapascals (MPa).

or both (A1.11) nominal stress calculation be meaningful beyond the yield point (A1.1) the extensive reduction in cross-section ensures. Under some circumstances it may be to express the tensile properties per unit

stress (nominal) sustained by the specimen on test. When the maximum stress is reached (A1.10), it shall be designated "Yield." When the maximum stress is reached, it shall be designated "Tensile strength."

A1.13 *gauge length*—the original length of that portion over which strain or change in length is determined.

A1.14 *elongation*—the increase in length produced by the test specimen by a tensile stress in units of length, usually millimeters or inches.

A1.15 *offset yield strength*—the stress at which the strain exceeds by a specified amount (the offset) an extension of the initial proportional portion of the stress-strain curve. It is expressed in force per unit area, usually megapascals.

A1.16 *modulus of elasticity*—the ratio of stress (nominal) to corresponding strain below the proportional limit of a material. It is expressed in force per unit area, usually megapascals (also known as *elastic modulus* or *Young's modulus*).

A1.17 *secant modulus*—the ratio of stress (nominal) to corresponding strain at any specified point on the stress-strain curve. It is expressed in force per unit area, usually megapascals and reported together with the specified stress or strain.

A1.18 *percent reduction of area (nominal)*—the difference between the original cross-sectional area measured at the point of rupture after breaking and after all retraction has ceased, expressed as a percent of the original area.

A1.19 *percent reduction of area (true)*—the difference between the original cross-sectional area of the test specimen and the minimum cross-sectional area within the gage boundaries prevailing at the moment of rupture, expressed as a percentage of the original area.

A1.20 *rate of loading*—the change in tensile load carried by the specimen per unit time. It is expressed in force per unit time, usually newtons per minute. The initial rate of loading can be calculated from the initial slope of the load versus time diagram.

A1.21 *rate of stressing (nominal)*—the change in tensile stress (nominal) per unit time. It is expressed in force per unit area per unit time, usually megapascals per minute. The initial rate of stressing can be calculated from the initial slope of the tensile stress (nominal) versus time diagram.

A1.22 *rate of straining*—the change in tensile strain per unit time. It is expressed either as strain per unit time, usually metres per metre minute, or percent elongation per unit time, usually percent elongation per minute. The initial rate of straining can be calculated from the initial slope of the tensile stress-versus-time diagram.

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A1.24 *rate of straining*—the change in tensile strain per unit time. It is expressed either as strain per unit time, usually metres per metre minute, or percent elongation per unit time, usually percent elongation per minute. The initial rate of straining can be calculated from the initial slope of the tensile stress-versus-time diagram.

A1.25 *rate of straining*—the change in tensile strain per unit time. It is expressed either as strain per unit time, usually metres per metre minute, or percent elongation per unit time, usually percent elongation per minute. The initial rate of straining can be calculated from the initial slope of the tensile stress-versus-time diagram.

A1.26 *rate of straining*—the change in tensile strain per unit time. It is expressed either as strain per unit time, usually metres per metre minute, or percent elongation per unit time, usually percent elongation per minute. The initial rate of straining can be calculated from the initial slope of the tensile stress-versus-time diagram.

A1.27 *rate of straining*—the change in tensile strain per unit time. It is expressed either as strain per unit time, usually metres per metre minute, or percent elongation per unit time, usually percent elongation per minute. The initial rate of straining can be calculated from the initial slope of the tensile stress-versus-time diagram.

section which may occur in a material under tensile stress.

A1.12 *yield strength*—the stress at which a material exhibits a specified limiting deviation from the proportionality of stress to strain. Unless otherwise specified, this stress will be the stress at the yield point and when expressed in relation to the Tensile Strength shall be designated either Tensile Strength at Yield or Tensile Stress at Yield as required under A1.2 (Fig. A1.2). (See *offset yield strength*.)

A1.13 *offset yield strength*—the stress at which the strain exceeds by a specified amount (the offset) an extension of the initial proportional portion of the stress-strain curve. It is expressed in force per unit area, usually megapascals.

A1.14 *modulus of elasticity*—the ratio of stress (nominal) to corresponding strain below the proportional limit of a material. It is expressed in force per unit area, usually megapascals (also known as *elastic modulus* or *Young's modulus*).

A1.15 *secant modulus*—the ratio of stress (nominal) to corresponding strain at any specified point on the stress-strain curve. It is expressed in force per unit area, usually megapascals and reported together with the specified stress or strain.

A1.16 *rate of loading*—the change in tensile load carried by the specimen per unit time. It is expressed in force per unit time, usually newtons per minute. The initial rate of loading can be calculated from the initial slope of the load versus time diagram.

A1.17 *rate of stressing (nominal)*—the change in tensile stress (nominal) per unit time. It is expressed in force per unit area per unit time, usually megapascals per minute. The initial rate of stressing can be calculated from the initial slope of the tensile stress (nominal) versus time diagram.

A1.18 *rate of straining*—the change in tensile strain per unit time. It is expressed either as strain per unit time, usually metres per metre minute, or percent elongation per unit time, usually percent elongation per minute. The initial rate of straining can be calculated from the initial slope of the tensile stress-versus-time diagram.

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cross-section, does not "neck down" and slip in the jaws.

A1.23 *Symbols*—The following symbols used for the above terms:

SYMBOL	TERM
W	Load
ΔW	Increment of load
L	Distance between gage marks at any point
L_0	Original distance between gage marks at point of rupture
ΔL	Distance between gage marks at point of rupture
	Increment of distance between gage marks
	elongation
	Minimum cross-sectional area at any point
A	Original cross-sectional area
ΔA	Increment of cross-sectional area
A_0	Cross-sectional area at point of rupture after breaking specimen
A_T	Cross-sectional area at point of rupture at the moment of rupture
t	Time
Δt	Increment of time
σ	Tensile stress
$\Delta \sigma$	Increment of stress
σ_T	True tensile stress
σ_{UT}	Tensile strength at break (nominal)
σ_{UT}	Tensile strength at break (true)
$\Delta \epsilon$	Strain
ϵ	Increment of strain
ϵ_U	Total strain at break
ϵ_T	True strain
ϵ_{EL}	Percent elongation
$Y.P.$	Yield point
E	Modulus of elasticity

A1.23.1 Relations between these various symbols may be defined as follows:

$$\sigma = W/A_0$$

$$\sigma_T = W/A_T$$

$$\sigma_{UT} = W/A_0 \text{ (where } W \text{ is breaking load)}$$

$$\sigma_{UT} = W/A_T \text{ (where } W \text{ is breaking load)}$$

$$\epsilon = \Delta L/L_0 = (L - L_0)/L_0$$

$$\epsilon_T = (L_T - L_0)/L_0$$

$$\epsilon_{EL} = \Delta L/L_0 = \ln L/L_0$$

$$\% E = [(L - L_0)/L_0] \times 100 = \epsilon \times 100$$

$$\text{Percent reduction of area (nominal)} = [(A_0 - A)/A_0] \times 100$$

$$\text{Percent reduction of area (true)} = [(A_0 - A_T)/A_0] \times 100$$

$$\text{Rate of loading} = \Delta W/\Delta t$$

$$\text{Rate of stressing (nominal)} = \Delta \sigma/\Delta t = (\Delta W/\Delta t)/A_0$$

$$\text{Rate of stressing (true)} = \Delta \sigma_T/\Delta t = (\Delta W/\Delta t)/A_T$$

$$\text{Rate of straining} = \Delta \epsilon/\Delta t = (\Delta L/\Delta t)/L_0$$

For the case where the volume of the test specimen does not change during the test, the following relations apply:

$$\sigma_T = \sigma \times (A_0/A_T)$$

$$\epsilon_T = \epsilon \times (L_0/L_T)$$

$$\epsilon_{EL} = \epsilon \times (L_0/L_T)$$

$$\% E = [(L - L_0)/L_0] \times 100 = \epsilon \times 100$$

$$\text{Percent reduction of area (nominal)} = [(A_0 - A)/A_0] \times 100$$

$$\text{Percent reduction of area (true)} = [(A_0 - A_T)/A_0] \times 100$$

$$\text{Rate of loading} = \Delta W/\Delta t$$

$$\text{Rate of stressing (nominal)} = \Delta \sigma/\Delta t = (\Delta W/\Delta t)/A_0$$

$$\text{Rate of stressing (true)} = \Delta \sigma_T/\Delta t = (\Delta W/\Delta t)/A_T$$

$$\text{Rate of straining} = \Delta \epsilon/\Delta t = (\Delta L/\Delta t)/L_0$$

For the case where the volume of the test specimen does not change during the test, the following relations apply:

$$\sigma_T = \sigma \times (A_0/A_T)$$

$$\epsilon_T = \epsilon \times (L_0/L_T)$$

$$\epsilon_{EL} = \epsilon \times (L_0/L_T)$$

$$\% E = [(L - L_0)/L_0] \times 100 = \epsilon \times 100$$

$$\text{Percent reduction of area (nominal)} = [(A_0 - A)/A_0] \times 100$$

$$\text{Percent reduction of area (true)} = [(A_0 - A_T)/A_0] \times 100$$

$$\text{Rate of loading} = \Delta W/\Delta t$$

$$\text{Rate of stressing (nominal)} = \Delta \sigma/\Delta t = (\Delta W/\Delta t)/A_0$$

$$\text{Rate of stressing (true)} = \Delta \sigma_T/\Delta t = (\Delta W/\Delta t)/A_T$$

$$\text{Rate of straining} = \Delta \epsilon/\Delta t = (\Delta L/\Delta t)/L_0$$

FIG. A1.1 Illustration of True Strain Equation

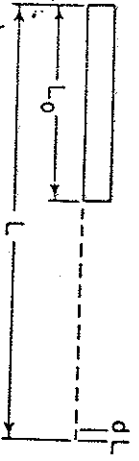


FIG. A1.2 Tensile Designations

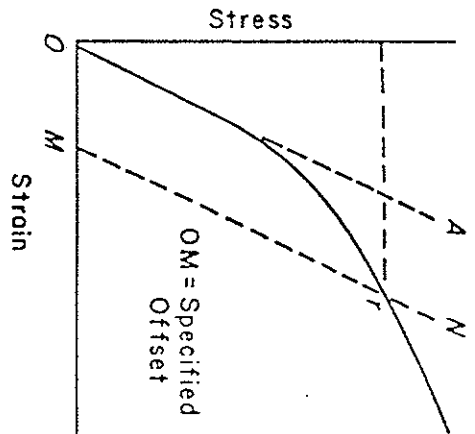
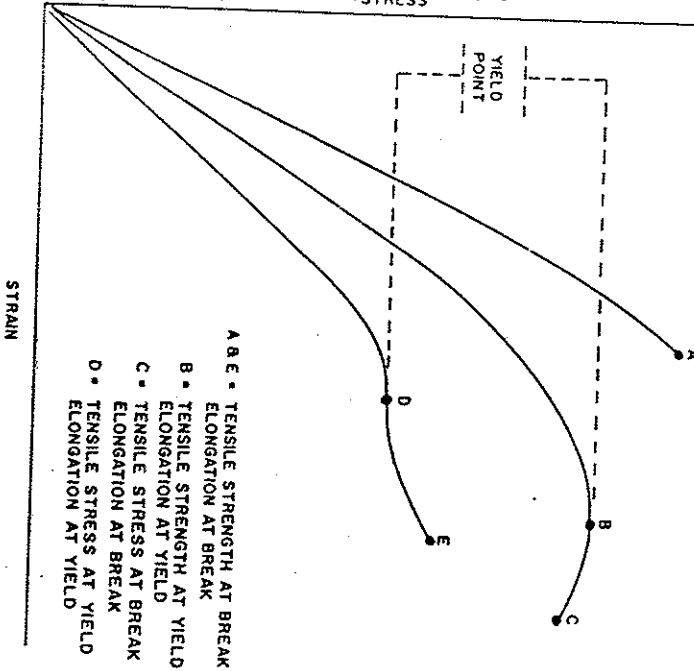


FIG. A1.3 Offset Yield Strength

APPENDIX

(Nonmandatory Information)

X1. TOE COMPENSATION

X1.1 In a typical stress - strain curve (Fig. X1.1) there is a toe region, AC, which does not represent a property of the material. It is an artifact caused by a takeup of slack, and alignment or seating of the specimen. In order to obtain correct values of such parameters as modulus, strain, and offset yield point, this artifact must be compensated for to give the corrected zero point on the strain or extension axis.

X1.2 In the case of a material exhibiting a region of Hookean (linear) behavior (Fig. X1.1), a continuation of the linear (CD) region of the curve is constructed through the zero-stress axis. This intersection (B) is the corrected zero-strain point from which all extensions or strains must be measured, including the yield offset (BE), if applicable. The elastic modulus can be determined by dividing the stress at any point

along the line CD (or its extension) by the same point (measured from point I zero-strain).

X1.3 In the case of a material which exhibit any linear region (Fig. X1.2), the toe correction of the zero-strain point by constructing a tangent to the maximum inflection point (I'). This is extended the strain axis at point B', the corrected point. Using point B' as zero strain, the point (C') on the curve can be divided at that point to obtain a secant modulus B' C'). For these materials with no linear attempt to use the tangent through the yield point as a basis for determination of strain point may result in unacceptable error.

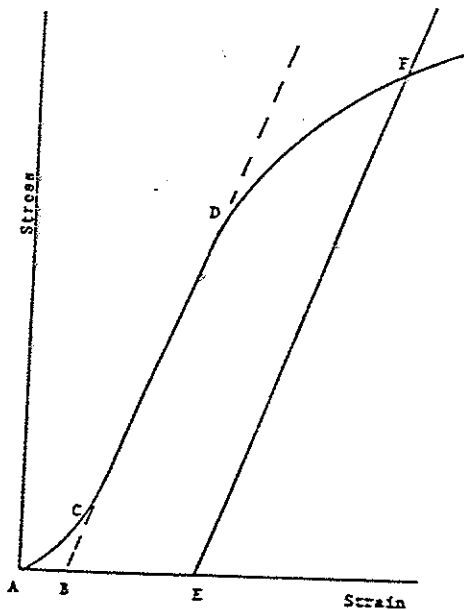


FIG. X1.1 Material with Hookean Region

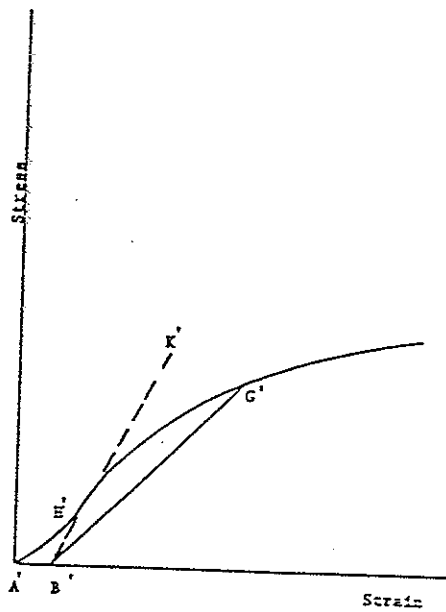


FIG. X1.2 Material with No Hookean Region
(Note that some chart recorders plot the mirror image of these graphs.)

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This standard is subject to revision at any time by the responsible technical committee and must be reviewed every five years and if not revised, either reapproved or withdrawn. Your comments are invited either for revision of this standard or for additional standards and should be addressed to ASTM Headquarters. Your comments will receive careful consideration at a meeting of the responsible technical committee, which you may attend. If you feel that your comments have not received a fair hearing you should make your views known to the ASTM Committee on Standards, 1916 Race St., Philadelphia, Pa. 19103.

degewise tests are not applicable for so thin that specimens meeting these cannot be cut. If specimen depth exceeds the

Less than 1.5 mm in Thick- specimens shall be 50 mm long by 10 sided flatwise on a 25-mm support

se of the formulas for simple beams cited methods for calculating results presumes it is small in comparison with the support, the formulas do not apply rigorously. Here machine sensitivity is such that these dimensions cannot be measured, provided the support span-to-depth ratio of 16 is satisfactory when the ratio of the tensile strength to shear strength is less than 8 to 1, but the support span-to-depth ratio must be increased for composite laminates having relatively low-shear strength in the plane of the laminate and relatively high tensile strength parallel to the support span.

7. Number of Test Specimens
7.1 At least five specimens shall be tested for each sample in the case of isotropic materials or molded specimens.
7.2 For each sample of anisotropic material in sheet form, at least five specimens shall be tested for each of the following conditions. Recommended conditions are flatwise and edgewise tests on specimens cut in lengthwise and crosswise directions of the sheet. For purposes of this test, "lengthwise" shall designate the principal axis of anisotropy and shall be interpreted to mean the direction of the sheet known to be stronger in flexure. "Crosswise" shall be the sheet direction known to be the weaker in flexure, and shall be at 90° to the lengthwise direction.

8. Conditioning

8.1 *Conditioning*—Condition the test specimens at 23 ± 2°C and 50 ± 5 % relative humidity for not less than 40 h prior to test in accordance with Procedure A of Practices D 618 for those tests where conditioning is required. In cases of disagreement, the tolerance shall be ± 1°C and ± 2 % relative humidity.

timers as soon as molded and not removing them until ready for testing.

8.2 *Test Conditions*—Conduct tests in the Standard Laboratory Atmosphere of 23 ± 2°C and 50 ± 5 % relative humidity, unless otherwise specified in the test methods. In cases of disagreement, the tolerance shall be ± 1°C and ± 2 % relative humidity.

9. Procedure

9.1 Method I—Procedure A:

9.1.1 Use an untested specimen for each measurement. Measure the width and depth of the specimen to the nearest 0.01 mm at the center of the support span. For specimens less than 2.5 mm in depth, measure the depth to the nearest 0.001 mm.

9.1.2 Determine the support span to be used as described in Section 6 and set the support span to within 1 % of the determined value.

9.1.3 If Table 1 is used, set the machine to the specified rate of crosshead motion, or as near as possible to it. If Table 1 is not used, calculate the rate of crosshead motion as follows and set the machine for the calculated rate, or as near as possible to it:

$$R = Z/2.7/d \quad (1)$$

where:

R = rate of crosshead motion, mm/min,

Z = support span, mm,

d = depth of beam, mm, and

Z = rate of straining of the outer fiber, mm/mm-min. Z shall equal 0.01.

In no case shall the actual crosshead rate differ from that specified by Table 1, or that calculated from Eq 1, by more than ± 50 %.

9.1.4 Align the loading nose and supports so that the axes of the cylindrical surfaces are parallel and the loading nose is midway between the supports. This parallelism may be checked by means of a plate with parallel grooves into which the loading nose and supports will fit when properly aligned. Center the specimen on the supports, with the long axis of the specimen perpendicular to the loading nose and supports.

9.1.5 Apply the load to the specimen at the specified crosshead rate, and take simultaneous

of the loading nose relative to the supports; either case, make appropriate corrections in the weighing system of the machine. Load deflection curves may be plotted to determine the flexural yield strength, secant or tangent modulus of elasticity, and the total work sustained by the area under the load-deflection curve.

9.1.6 Terminate the test if the maximum strain in the outer fibers has reached 0.05 mm (Notes 8 and 9). The deflection at which this strain occurs may be calculated by the r equal 0.05 mm/mm as follows:

$$D = rL^2/6d$$

where:

D = midspan deflection, mm,

r = strain, mm/mm,

L = support span, mm, and

d = depth of beam, mm.

NOTE 8—For some materials the increase in rate provided under Procedure B may induce specimen to yield or rupture, or both, within required 5 % strain limit.

NOTE 9—Beyond 5 % strain, these test methods not applicable, and some other property may be used (for example, Test Method D 638 may be used).

9.2 Method II—Procedure A:

9.2.1 See 9.1.1.

9.2.2 See 9.1.2.

9.2.3 If Table 2 or 3 is used, set the machine for the specified rate of crosshead motion, near as possible to it. If Table 2 or 3 is not used, calculate the rate of crosshead motion as follows and set the machine as near as possible that calculated rate for a load span of one of the support span:

$$R = 0.185Z/2.7/d$$

For a load span of one half of the support:

$$R = 0.167Z/2.7/d$$

where:

R = rate of crosshead motion, mm/min

L = support span, mm,

d = depth of beam, mm, and

Z = rate of straining of the outer fibers, mm-min. Z shall equal 0.01.

In no case shall the actual crosshead rate

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10. Retests

10.1 Values for properties at rupture shall not be calculated for any specimen that breaks at some obvious, fortuitous flaw, unless such flaws constitute a variable being studied. Retests shall be made for any specimen on which values are not calculated.

11. Calculation

11.1 Maximum Fiber Stress, Method 1—

When a beam of homogeneous, elastic material is tested in flexure as a simple beam supported at two points and loaded at the midpoint, the maximum stress in the outer fibers occurs at midspan. This stress may be calculated for any point on the load - deflection curve by the following equation (Notes 10 and 11):

$$S = 3PL/2bd^2 \quad (3)$$

where:

S = stress in the outer fibers at midspan, MPa,

P = load at a given point on the load-deflection curve, N,

L = support span, mm,

b = width of beam tested, mm, and

d = depth of beam tested, mm.

NOTE 10—Equation 3 applies strictly to materials for which the stress is linearly proportional to strain up to the point of rupture and for which the strains are small. Since this is not always the case, a slight error will be introduced in the use of this equation. The equation will, however, be valid for comparison data and specification values up to the maximum fiber strain of 5 % for specimens tested by the procedure herein described. It should be noted that the maximum stress may not occur in the outer fibers for a highly orthotropic laminate. Laminated beam theory must be applied to determine the maximum tensile stress at failure. Thus, Eq 3 yields an apparent strength based on homogeneous beam theory. This apparent strength is highly dependent on the ply-stacking sequence for highly orthotropic laminates.

NOTE 11—The above calculation is not valid if the specimen is slipping excessively between the supports.

11.2 Maximum Fiber Stress for Beams Tested at Large Support Spans, Method 1—

If support span-to-depth ratios greater than 16 to 1 are used such that deflections in excess of 10 % of

the support span occur, the maximum stress for a simple beam can be reasonably approximated with the following equation (Note 12):

$$S = (3PL/2bd^2) \times [1 + 6(D/L)^2 - 4(d/L)(D/L)] \quad (3a)$$

where S , P , L , b , and d are the same as for Eq 3 and D is the deflection in millimetres of the centerline of the specimen at the middle of the support span.

NOTE 12—When large support span-to-depth ratios are used, significant end forces are developed at the supports which affect the moment in a simply supported beam. An approximate correction factor is given in Eq 3a to correct for these end forces in large support span-to-depth ratio beams where relatively large deflections exist.

11.3 Maximum Fiber Stress, Method 11—

When a beam is loaded in flexure at two central points and supported at two outer points, the maximum stress in the outer fibers occurs between the two central loading points that define the load span (Fig. 2). This stress may be calculated for any point on the load - deflection curve for relatively small deflections by the following equation for a load span of one-third of the support span (Note 13):

$$S = PL/bd^2 \quad (3b)$$

for a load span of one-half of the support span:

$$S = 3PL/4bd^2 \quad (3c)$$

where:

S = stress in the outer fiber throughout the load span, MPa,

P = load at a given point on the load deflection curve, N,

L = support span, mm,

b = width of beam, mm, and

d = depth of beam, mm.

NOTE 13—The limitations defined for Eq 3 in Notes 10 and 11 apply also to Eqs 3a, 3b, 3c, 3d, and 3e.

11.4 Maximum Fiber Stress—Method 11 for Beams Tested at Large Support Spans—

If support span-to-depth ratios greater than 16 to 1 are used with resultant deflections in excess of 10 % of the support span occurring, the maximum stress may be reasonably approximated with the following formula for a load span of

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11.5 Flexural Strength

where S , P , L , b , and d are the same as for Eq 3 and D = maximum deflection of the center of the beam in millimetres.

11.5 Flexural Strength (*Modulus of Rupture*)—The flexural strength is equal to the maximum stress in the outer fibers at the moment of break (for highly orthotropic laminates, see Note 10). It is calculated in accordance with Eq 3, 3a, 3b, 3c, 3d, and 3e by letting P equal the load at the moment of break. If it is not applicable, in this case, it is suggested that yield strength, if applicable, be calculated at the corresponding strain be reported in (see 11.6, 11.8, and 11.9).

11.6 Flexural Yield Strength—Some materials that do not break at outer fiber strains to 5 % may give load - deflection curves that show a point, Y , at which the load does not increase with an increase in deflection. In such cases, the flexural yield strength may be calculated in accordance with Eq 3, 3a, 3b, or by letting P equal the load at point Y .

11.7 Flexural Offset Yield Strength—Offset yield strength is the stress at which the stress-strain curve deviates by a given strain (offset) from the tangent to the initial straight portion of the stress - strain curve. The value of the offset must be given whenever this property is calculated.

NOTE 14—This value may differ from flexural strength defined in 11.6. Both methods of calculation are described in the Annex to Method D 790M.

11.8 Stress at a Given Strain—The maximum fiber stress at any given strain may be calculated in accordance with Eq 3, 3a, 3b, 3c, and 3e by letting P equal the load read from the load - deflection curve at the deflection corresponding to the desired strain (for highly orthotropic laminates, see Note 10).

11.9 Maximum Strain, Method 1—The maximum strain in the outer fibers occurs at the point of rupture and may be calculated as follows:

$$\epsilon = 6bd/L^2$$

where:

ϵ = maximum strain in the outer fibers, mm/mm,

Method 1 (3-Point Loading)

Nominal Specimen	Specimen width	Specimen length	Support	Cross-section	Ratio
Specimen	men	Length	Support	Mc	
Depth			Stress	Ratio	

Depth, mm	Width, mm	Depth, mm (100 A), m
16.0	16.0	16.0

$L_1/a = 10.0$				
1	25	50	16	0
2	25	50	32	0
3	25	60	48	1

3	25	50	1/5	1
4	10	80	6/1	1
5	10	100	8/1	2
6	10	125	9/6	2

10	10	200	100	4
15	20	270	240	6
20	20	350	320	8
25	25	450	400	10

$L/d \approx 32$ to 1				
25	25	450	4000	10
1	25	50	32	1

2	25	80	6.1	3.6
3	25	125	9.6	5.1
4	10	150	128	6.1
5	10	200	160	8.1

3	10	200	100	6.
6	10	250	192	10.
10	10	350	320	17.
15	20	550	480	25.

20	20	700	6.10	34.
25	25	900	8.00	42.6

[illegible]

1	10	160	10
4	10	200	10
5	10	240	13
6	10	270	16

25	25	1,100	66
20	20	900	53
15	20	680	40
10	10	450	26

$L/d \approx 60$ to 1
 1 25 75 60 6

2	25	150	120	12
3	25	200	180	18
4	10	300	240	24
5	10	350	300	30

5	20	250	300	30
6	10	400	360	36
10	10	700	600	60
15	20	1000	900	90

Rate	20	25	1000	1500	1750
20	20	1000	1750	1750	1750
25	25	1000	1500	1500	1500

^a Rates indicated are for Procedure A where stratum

0.01 mm/mm·min. To obtain rates for Procedure B strain rate is 0.10 mm/mm·min., multiply these values by 10. Procedure A is to be used for all specification points.

Recommended Dimensions for Test Specimens of Section 6.3 and 6.5 for Various Support Span-to-Depth Ratios (See Note 7)

Method II (4-Point Loading at 1/4 Points, Fig. 2 (A))

Specimen Depth, mm	Specimen Length, mm	Support Span, mm	Load Span, mm	Rate of Cross-head Motion (Procedure A), mm/min ^a
$L/d = 16 \text{ to } 1$				
1	25	16	5.3	0.47
2	50	32	10.7	0.94
3	25	48	16.0	1.4
4	60	64	21.3	1.9
5	80	80	26.7	2.4
6	100	96	32.0	2.8
10	125	125	40.0	3.5
15	200	160	53.3	4.7
20	270	240	80.0	7.1
25	350	320	106.7	9.5
25	450	400	133.3	11.8
$L/d = 32 \text{ to } 1$				
1	25	32	10.7	1.9
2	25	64	21.3	3.8
3	125	96	32.0	5.7
4	150	128	42.7	7.6
5	200	160	53.3	9.5
6	250	192	64.0	11.4
10	350	320	106.7	18.9
15	550	480	160.0	28.4
20	700	640	213.3	37.9
25	900	800	266.7	47.4

$L/d = 40 \text{ to } 1$

1	25	60	40	13.3	3.0
2	25	100	80	26.7	5.9
3	25	150	120	40.0	8.9
4	10	200	160	53.3	11.8
5	10	240	200	66.7	14.8
6	10	270	240	80.0	17.8
10	10	450	400	133.3	29.6
15	15	680	600	200.0	44.4
20	20	900	800	266.7	59.2
25	25	1100	1000	333.3	74.0

$L/d = 60 \text{ to } 1$

1	25	75	60	20	6.7
2	25	150	120	40	13.3
3	25	200	180	60	20.0
4	10	300	240	80	26.6
5	10	350	300	100	33.3
6	10	400	360	120	40.0
10	10	700	600	200	66.6
15	15	1000	900	266.7	99.9
20	20	1400	1200	400	133.0
25	25	1800	1500	500	166.0



Penelitian Sifat Mekanis Pipa FRP Helikal Filament Winding Produksi PT Jaya Fibrindo Karsa Pratama

Kuatrinhus Wijaya, Prof. Ir. Jama'sri, Ph.D.

Universitas Gadjah Mada, 1998 | Diunduh dari <http://etd.repository.ugm.ac.id/>

Notes indicated are for Procedure A where strain rate is 0.01 mm/mm-min. To obtain speeds for Procedure B where strain rate is 0.10 mm/mm-min, multiply these values by 10. Procedure A is to be used for all specification purposes, unless otherwise indicated in the specifications. See 9.2.3 for the method of calculation.

TABLE 3 Recommended Dimensions for Test Specimens of Sections 6.3 and 6.5 for Various Support Span-to-Depth Ratios (See Note 7)

Method II (4-Point Loading at 1/4 Points, Fig. 2 (B))

Specimen Depth, mm	Specimen Width, mm	Specimen Length, mm	Support Span, mm	Load Span, mm	Rate of Cross-head Motion (Procedure A), mm/min ^a
$L/d = 16 \text{ to } 1$					
1	25	50	16	8	0.42
2	25	50	32	16	0.85
3	25	60	48	24	1.3
4	10	80	64	32	1.7
5	10	100	80	40	2.1
6	10	125	96	48	2.6
10	10	200	160	80	4.3
15	15	270	240	120	6.4
20	20	350	320	160	8.6
25	25	450	400	200	10.7
$L/d = 32 \text{ to } 1$					
1	25	50	32	16	1.7
2	25	80	64	32	3.4
3	25	125	96	48	5.1
4	10	150	128	64	6.8
5	10	200	160	80	8.6
6	10	250	192	96	10.3
10	10	350	320	160	17.1
15	15	550	480	240	25.7
20	20	700	640	320	34.2
25	25	900	800	400	42.8

$L/d = 40 \text{ to } 1$

1	25	60	40	20	2.7
2	25	100	80	40	5.3
3	25	150	120	60	8.0
4	10	200	160	80	10.7
5	10	240	200	100	13.4
6	10	270	240	120	16.0
10	10	450	400	200	26.7
15	15	680	600	300	40.0
20	20	900	800	400	53.4
25	25	1100	1000	500	66.8

$L/d = 60 \text{ to } 1$

1	25	75	60	30	6.0
2	25	150	120	60	12.0
3	25	200	180	90	18.0
4	10	300	240	120	24.0
5	10	350	300	150	30.0
6	10	400	360	180	36.0
10	10	700	600	300	60.0
15	15	1000	900	450	90.0
20	20	1400	1200	600	120.0
25	25	1800	1500	750	150.0

Notes indicated are for Procedure A where strain rate is 0.01 mm/mm-min. To obtain rates for Procedure B where strain rate is 0.10 mm/mm-min, multiply these values by 10. Procedure A is to be used for all specification purposes, unless otherwise indicated in the specifications. See 9.2.3 for the method of calculation.

APPENDIX

(Nonmandatory Information)

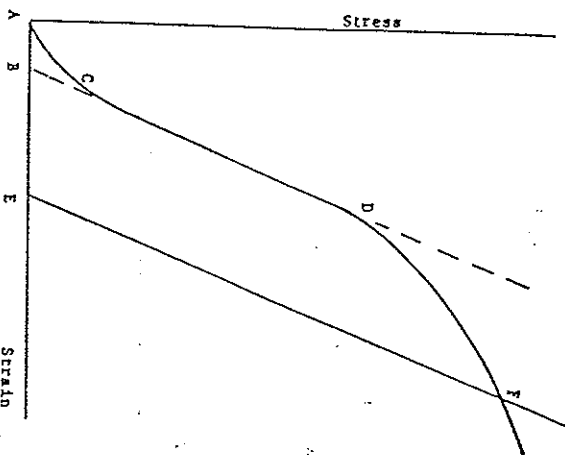
X1. TOE COMPENSATION

X1.1 In a typical stress-strain curve (Fig. X1.1) there is a toe region, AC , that does not represent a property of the material. It is an artifact caused by a take-up of slack, and alignment or seating of the specimen. In order to obtain correct values of such parameters as modulus, strain, and offset yield point, this artifact must be compensated for to give the corrected zero point on the strain or extension axis.

X1.2 In the case of a material exhibiting a region of Hookean (linear) behavior (Fig. X1.1), a continuation of the linear (CD) region of the curve is constructed through the zero-stress axis. This intersection (B) is the corrected zero-strain point from which all extensions or strains must be measured, including the yield offset (BE), if applicable. The elastic modulus can be determined by dividing the stress at any

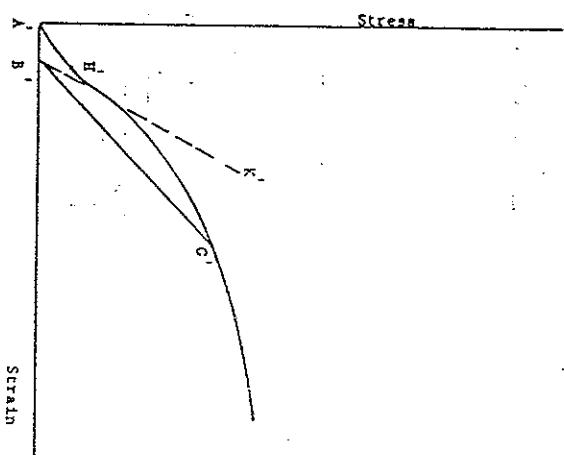
point along the line CD (or its extension) by the strain at the same point (measured from point B , defined as zero-strain).

X1.3 In the case of a material that does not exhibit any linear region (Fig. X1.2), the same kind of toe correction of the zero-strain point can be made by constructing a tangent to the maximum slope at the inflection point (H'). This is extended to intersect the strain axis at point B' , the corrected zero-strain point. Using point B' as zero strain, the stress at any point (G') on the curve can be divided by the strain at that point to obtain a secant modulus (slope of line $B'G'$). For those materials with no linear region, any attempt to use the tangent through the inflection point as a basis for determination of an offset yield point may result in unacceptable error.



NOTE—Some chart recorders plot the mirror image of this graph.

FIG. X1.1 Material with Hookean Region



NOTE—Some chart recorders plot the mirror image of this graph.

FIG. X1.2 Material with No Hookean Region

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