

UNDERGRADUATE THESIS

***PATH PLANNING OPTIMIZATION FOR WHEELED ROBOT IN A MAZE
ENVIRONMENT***



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**ELECTRONICS AND INSTRUMENTATION STUDY PROGRAM
DEPARTMENT OF COMPUTER SCIENCE AND ELECTRONICS
FACULTY OF MATHEMATICS AND NATURAL SCIENCES
UNIVERSITAS GADJAH MADA
YOGYAKARTA**

2024

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Proposed to fulfil the requirement for
Bachelor of Electronics and Instrumentation



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SKRIPSI

**PATH PLANNING OPTIMIZATION FOR WHEELED ROBOT IN A MAZE
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Telah dipersiapkan dan disusun oleh

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Telah dipertahankan di depan Tim Penguji
pada tanggal 05 Januari 2024


Susunan Tim Penguji



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Pembimbing

Mengetahui,
a.n. Dekan FMIPA UGM
Wakil Dekan Bidang Pendidikan, Pengajaran
dan Kemahasiswaan



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