

II.4.	<i>Filtering</i>	14
II.5.	Model 3D	15
II.6.	Validasi Model.....	17
II.7.	<i>Level of Accuracy (LoA)</i>	18
II.8.	<i>Level of Detail (LoD)</i>	18
BAB III	20
III.1.	Lokasi Penelitian	20
III.2.	Peralatan dan Bahan	22
III.2.1.	Peralatan Penelitian	22
III.2.2.	Bahan Penelitian	23
III.3.	Tahapan Penelitian	24
III.3.1.	Perencanaan Pengukuran	25
III.3.2.	Akuisisi Data dengan Topcon GLS 2000	28
III.3.3.	Pengolahan Data <i>Point Clouds</i>	30
III.3.4.	Validasi Data Pengukuran	32
III.3.5.	Visualisasi Model	33
BAB IV	36
IV.1.	<i>Point Clouds</i> Hasil Pemindaian	36
IV.1.1.	<i>Scan World</i> Metode <i>Backsighting</i>	36
IV.1.2.	<i>Scan World</i> Metode <i>Free Scanning</i>	37
IV.1.3.	Persebaran <i>Point Clouds</i> pada <i>Scan World</i>	38
IV.1.4.	Identifikasi Kesalahan pada <i>Scan World</i>	40
IV.2.	Registrasi Data <i>Point Clouds</i>	41
IV.2.1.	Registrasi Metode <i>Traverse</i>	41
IV.2.2.	Registrasi Metode <i>Cloud to Cloud</i>	43
IV.2.3.	Integrasi Hasil Registrasi <i>Traverse</i> dan <i>Cloud to Cloud</i>	44



IV.2.4. Noise Filtering	46
IV.3. Validasi Data <i>Point Clouds</i>	47
IV.3.1. Perbandingan Ukuran Sampel Lapangan dan Model	48
IV.3.2. Perhitungan <i>RMSe</i>	52
IV.4. Model 3D.....	55
IV.4.1. Model Struktur Jembatan	55
IV.4.2. Model <i>Terrain</i>	56
IV.4.3 Kontrol Kualitas Model	57
IV.5. Visualisasi Data.....	58
IV.5.1. Integrasi 3D Model Jembatan dan <i>Terrain</i>	58
IV.5.2. <i>Rendering</i> di Perangkat Lunak Enscape.....	60
BAB V	62
V.1. Kesimpulan	62
V.2. Saran	62
DAFTAR PUSTAKA.....	64
LAMPIRAN	68