



DAFTAR PUSTAKA

- Aji, M., Wibowo, A., Hunaini, F., & Usman Effendi, D. (2018). PERANCANGAN DAN PEMBUATAN PURWARUPA LINE FOLLOWER FORKLIFT. *Jurnal WIDYA TEKNIKA*, 26(2), 194–206.
- Ceraolo, M., Lutzemberger, G., Scarpelli, C., Bonelli, G. P., & Piazza, T. (2020). Hybridisation of forklift trucks. *IET Electrical Systems in Transportation*, 10(1), 116–123.
- Firdaus, R. (2015). *RANCANG BANGUN PROTOTIPE FORKLIFT MANUAL DENGAN KAPASITAS ANGKAT 200 KG (PROSES PEMBUATAN)*.
- Johra, F.-T., & Shuvo, Md. M. H. (2016). Detection of breast cancer from histopathology image and classifying benign and malignant state using fuzzy logic. *2016 3rd International Conference on Electrical Engineering and Information Communication Technology (ICEEICT)*, 1–5. <https://doi.org/10.1109/CEEICT.2016.7873137>
- Klir, G. J., st. Clair, U., & Yuan, B. (1997). *Fuzzy set theory: foundations and applications*. Prentice-Hall, Inc.
- Kusumadewi, S., & Guswaludin, I. (2005). Fuzzy Multi-Criteria Decision Making. *Media Informatika*, 3(1), 25–38. <https://journal.uii.ac.id/media-informatika/article/view/24>
- Kusumadewi, S., & Purnomo, H. (2010). Aplikasi logika Fuzzy untuk pendukung keputusan. *Graha iImu*. Yogyakarta.
- Latha, N. A., Murthy, B. R., & Kumar, K. B. (2016). Distance sensing with ultrasonic sensor and Arduino. *International Journal of Advance Research, Ideas and Innovations in Technology*, 2(5), 1–5.
- Pandian, P., ... V. D. S.-P., & 2016, undefined. (2016). Development of fuzzy based intelligent decision model to optimize the blind spots in heavy transport vehicles. *hrcak.srce.hr*, 28(1), 1–10. <https://hrcak.srce.hr/file/227337>
- Paulet, M. V., Salceanu, A., & Neacsu, O. M. (2016). Ultrasonic radar. *2016 International Conference and Exposition on Electrical and Power Engineering (EPE)*, 551–554. <https://doi.org/10.1109/ICEPE.2016.7781400>
- Qidwai, U. (2009). Fuzzy blind-spot scanner for automobiles. *2009 IEEE Symposium on Industrial Electronics and Applications, ISIEA 2009 - Proceedings*, 2, 758–763. <https://doi.org/10.1109/ISIEA.2009.5356356>



- Riandi, R., Brillian Kharisma, O., & Ullah, A. (2018). Pengembangan Sistem Deteksi Objek berbasis Teknologi Internet of Things terintegrasi Telegram Bot menggunakan Ultrasonik HCS04R. *ejurnal.uin-suska.ac.id*, 2579–5406. <http://ejurnal.uin-suska.ac.id/index.php/SNTIKI/article/view/5928>
- Shen, X., & Marks, E. (2016). Forklift operator visibility evaluation in a manufacturing environment. *Journal of Safety, Health & Environmental Research*, 12(2), 317–321.
- Shete, R. G., Kakade, S. K., & Dhanvijay, M. (2021). A Blind-spot Assistance for Forklift using Ultrasonic Sensor. *2021 IEEE International Conference on Technology, Research, and Innovation for Betterment of Society, TRIBES 2021*. <https://doi.org/10.1109/TRIBES52498.2021.9751672>
- Song, K.-T., Chen, C.-H., & Huang, C.-H. C. (2004). Design and experimental study of an ultrasonic sensor system for lateral collision avoidance at low speeds. *IEEE Intelligent Vehicles Symposium, 2004*, 647–652. <https://doi.org/10.1109/IVS.2004.1336460>
- Susilo, F. (2006). Himpunan dan logika kabur serta aplikasinya. *Yogyakarta: Graha Ilmu*.
- Ulrich, M., Dolar, C., Marbach, C., & Engelhart, C. (2020). Collision Warning System for Forklift Trucks. *ATZheavy duty worldwide*, 13(4), 16–21. <https://doi.org/10.1007/s41321-020-0109-4>
- Vicky, M., Anggraini, N., Shofi, I. M., Wardhani, L. K., Hakiem, N., & Rosyadi, T. (2021). Object Detection System in Blind Spot Dump Truck Area Using Fuzzy Logic with Sugeno Method. *2021 9th International Conference on Cyber and IT Service Management, CITSM 2021*. <https://doi.org/10.1109/CITSM52892.2021.9588823>
- Wahyudi Suardika, K., Gandhiadi, G., & Putu Ida Harini, L. (2018). *PERBANDINGAN METODE TSUKAMOTO, METODE MAMDANI DAN METODE SUGENO UNTUK MENENTUKAN PRODUKSI DUPA (Studi Kasus : CV. Dewi Bulan)*. 7(2), 180–186. <https://doi.org/10.24843/MTK.2018.v07.i02.p201>
- Zhmud, V. A., Kondratiev, N. O., Kuznetsov, K. A., Trubin, V. G., & Dimitrov, L. V. (2018). Application of ultrasonic sensor for measuring distances in robotics. *Journal of Physics: Conference Series*, 1015(3), 032189. <https://doi.org/10.1088/1742-6596/1015/3/032189>