

## DAFTAR PUSTAKA

- Alldatasheet. (n.d.-a). *MG90s Datasheet (PDF)*.  
<https://pdf1.alldatasheet.com/datasheet-pdf/view/1132104/ETC2/MG90S.html>
- Alldatasheet. (n.d.-b). *OV5647 Datasheet (PDF) – OmniVision Technologies, Inc.*  
Retrieved June 24, 2022, from <https://pdf1.alldatasheet.com/datasheet-pdf/view/587045/OMNIVISION/OV5647.html>
- Budi Setiawan, I. (2022). *Perancangan dan Implementasi Sistem Kendali Semi Otomatis pada Remotely Operated Vehicle Berbasis Kendali PID*. Universitas Gadjah Mada.
- Dere, E., Ozcan, M., & Canan, S. (2018). *Three Axis Gimbal Design And Its Application*. 1–4.
- Garante, K. (2021). Perancangan dan Penerapan Stabilized Kamera 2-Axis pada Perahu. *E-Proceeding of Engineering*, 73.
- Gastreich, W. (2018). *What is a Servo Motor and How it Works. ?*  
<https://realpars.com/servo-motor/>
- Haris, M. S., Dharmawan, A., & Atmaji, C. (2017). Sistem Kendali Gimbal 2-Sumbu Sebagai Tempat Kamera Pada Quadrotor Menggunakan PID Fuzzy. *IJEIS (Indonesian Journal of Electronics and Instrumentation Systems)*, 7(2), 185.  
<https://doi.org/10.22146/ijeis.24220>
- Indo Frans, S. (2022). *Deteksi Objek Sederhana Citra Bawah Air Berdasarkan Warna dan Morfologi Pada Remotely Operated Vehicle (ROV)*. Universitas Gadjah Mada.
- Malaca, M., Mademlis, I., Cunha, R., Sampaio, V., Guerreiro, B., Nousi, P., Tefas, A., & Pitas, I. (2019). *Gimbal Control for Vision-based Target Tracking Computational UAV Cinematography for Intelligent Shooting Based on Semantic Visual Analysis Gimbal Control for Vision-based Target Tracking*.
- Mohazzabi, P. (2017). Archimedes' Principle Revisited. *Journal of Applied Mathematics and Physics*, 5(4).
- Priyambodo, T. K. (2017). Implementasi Sistem Kendali PID pada Gimbal Kamera 2-sumbu dengan Aktuator Motor Brushless. *IJEIS (Indonesian Journal of Electronics and Instrumentation Systems)*, 7(2), 111.  
<https://doi.org/10.22146/ijeis.18238>
- Raspberrypi.com. (n.d.). *Raspberry pi 4 Model B*. Retrieved June 24, 2022, from <https://www.raspberrypi.com/products/raspberry-pi-4-model-b/specifications/>
- Regner, D. J., Salazar, J. D., Buschinelli, P. V., Machado, M., Oliveira, D., Santos, J. M., Marinho, C. A., & Pinto, T. C. (2021). Object tracking control using a gimbal mechanism. *International Archives of the Photogrammetry, Remote Sensing and Spatial Information Sciences - ISPRS Archives*, 43(B1-2021), 189–196. <https://doi.org/10.5194/isprs-archives-XLIII-B1-2021-189-2021>

- Sivanandam, S. N., Sumathi, S., & Deepa, S. N. (2007). Introduction to fuzzy logic using MATLAB. In *Introduction to Fuzzy Logic using MATLAB*. <https://doi.org/10.1007/978-3-540-35781-0>
- Sutadi, N. (2013). Pembuktian Hukum Snellius Tentang Pembiasan Cahaya Pada Medium Udara-Air Menggunakan Logger Pro. *Prosiding Seminar Nasional*, 45–48.
- Versus.com. (2022). *Raspberry Pi 3 Model B Plus vs Raspberry Pi 4 Model B*. <https://versus.com/en/raspberry-pi-3-model-b-plus-vs-raspberry-pi-4-model-b>
- Visualstudio. (2022). *Overview*. <https://code.visualstudio.com/docs>