

DAFTAR PUSTAKA

- Afif, M., Habibullah, N., Budi, M., & Ekawati, E. (2015). Pemodelan dan Rancang Bangun Autonomous Underwater Vehicle dengan Enam Propeller. In *Seminar Nasional Instrumentasi, Kontrol dan Otomasi (SNIKO)*.
- Anam, H., & Setiawan, J. D. (2015). SIMULASI DAN ANALISA DINAMIKA REMOTELY OPERATED VEHICLE (ROV). In *Jurnal Teknik Mesin S-1* (Vol. 3, Issue 1).
- Fossen, T. I. (1991). Nonlinear modeling and control of underwater vehicles. Teknologi informasi, matematika dan teknik elektro.
- Fossen, T. I. (2002). *Marine Control Systems: Guidance, Navigation and Control of Ships, Rigs and Underwater Vehicles*. Trondheim, Norway.
- Fossen, T. I. (2011). Handbook of marine craft hydrodynamics and motion control. John Wiley & Sons.
- Kabanov, A., Kramar, V., & Ermakov, I. (2021). Design and modeling of an experimental rov with six degrees of freedom. *Drones*, 5(4). <https://doi.org/10.3390/drones5040113>
- Malachowski, T., & Dudek, F. (2020). Project of a 6 Degrees of Freedom Remotely Operated Vehicle propulsion system with azimuthal thrusters. *2020 Global Oceans 2020: Singapore - U.S. Gulf Coast*. <https://doi.org/10.1109/IEEECONF38699.2020.9389419>
- Putri Syahna, Q. 2019. *Analisis Respon Sistem Kendali LQR (Linear Quadratic Regulator) pada Simulasi Gimbal Kamera Dua Sumbu*. Skripsi. Departemen Fisika. Sains dan Teknologi. Universitas Islam Negeri Syarif Hidayatullah Jakarta.
- R G, R. K., & S, P. P. (2013). Design and Control of Autonomous Underwater Vehicle for Depth Control Using LQR Controller. In *International Journal of Science and Research* (Vol. 5). www.ijsr.net
- Rizki Imaduddin, I. 2016. *Desain Kontrol Tracking Underactuated AUV pada Bidang Horizontal Menggunakan State Dependent Riccati Equations (SDRE)-LQT*. Thesis. Departemen Teknik Sistem Pengaturan. Teknologi Industri. Institut Teknologi Sepuluh Nopember Surabaya.
- SNAME. (1950). *Nomenclature for treating the motion of a submerged body through a fluid JR*. New York : Technical and Research Bulletin: 1-5.
- Vondřich, J., & Thöndel, E. (n.d.). *MODELING OF LQR CONTROL WITH MATLAB*.
- Wu, C. (2018). *6-Dof Modeling and Control of a Remotely Operated Vehicle*. Flinders University.